

Operating Systems

Scheduling and Deadlocks

Daniel Gruss

2023-11-07





Time	Monday	Tuesday	Wednesday	Thursday	Triday	Saturday	Sunday
07.00							
08.00							
09.00							
10.00							
11.00							
12.00							
13.00							
14.00							
15.00							
16.00							















• No "right" answer

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- No "right" answer
- always a trade-off

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Some Scheduling Ideas Already

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- Short homework first: Shortest Job First (SJF)

```
CPU[|| 1.8%]
Mem[|| 41 1M/489M]
```

VS

2.6%]

0.7%]

9[||

2[0.0%]	10[1.3%]	18[0.0%]	26	0.0%]
3[0.7%]	11[]	1.3%]	19[0.0%]	27	0.0%]
4[0.7%]	12[0.0%]	20[0.0%]	28	0.0%]
5[0.7%]	13[0.7%]	21[0.7%]	29[0.0%]
6[2.0%]	14[1.3%]	22	0.0%]	30[0.0%]
7[0.0%]	15[0.7%]	23[0.7%]	31[0.0%]
8[0.0%]	16[]	1.3%]	24[0.7%]	32[]]	2.6%]

17[

0.0%]

25

0.0%]

Similar design challenges as with PRAs:

- latency
- throughput
- fairness

HAVING A TIRE BLOWOUT A WEEK AFTER HITTING A SIDECURB PRINCIPLE OF LOAN

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- Starvation: task doesn't make any progress due to other tasks

• takes a workload as input

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- decides which tasks to do first
- Performance metric (throughput, latency) as output
- Only **preemptive**, work-conserving schedulers to be considered

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 - compute-bound: only use the CPU
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 - mixed

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First-In-First-Out (FIFO)

-

• aka first-come-first-serve

First-In-First-Out (FIFO)

- aka first-come-first-serve
- Run tasks in order of arrival until they complete or yield

Tasks	FIFO	
(1)		
(2)		
(3)		
(4)		
(5)		

SJF - **Shortest Job First**

• FIFO optimized for throughput - other extreme: optimize for latency

SJF - **Shortest Job First**

- FIFO optimized for throughput other extreme: optimize for latency
- \rightarrow schedule the shortest job first (SJF)

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Tasks	SJF
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Time















• No more Express-Kassen!



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- Skip ahead in the waiting line until everybody in front of you has the same or fewer items



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- No more Express-Kassen!
- Skip ahead in the waiting line until everybody in front of you has the same or fewer items
- $\rightarrow \ \text{current customer interrupted}$
- $\rightarrow\,$ full basket you have to wait...

Round Robin















 \bullet fighting starvation: schedule tasks in a round robin fashion



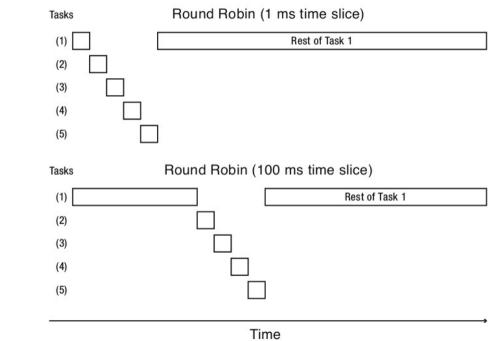
- fighting starvation: schedule tasks in a round robin fashion
- compromise between FIFO and SJF

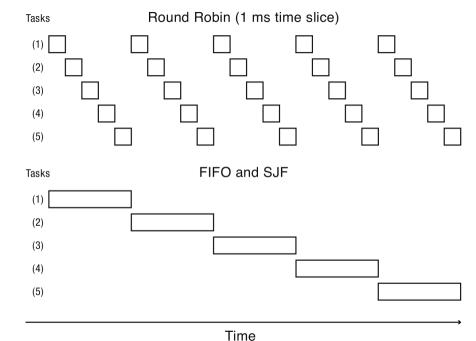


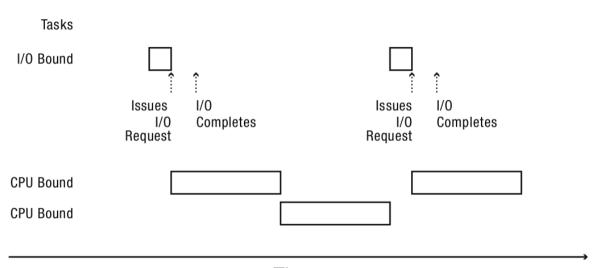
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- not finished? → back in line





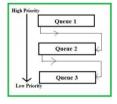


Time

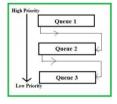
Multi-level Feedback Queue (MFQ)

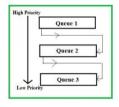
- Goals:
 - Latency
 - Low overhead
 - Starvation freedom
 - Some tasks are high/low priority
 - Fairness (among equal priority tasks)
- Not perfect at any of them!
 - Used in Linux (and probably Windows, MacOS)





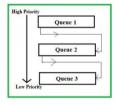




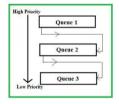


• Set of Round Robin queues

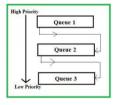




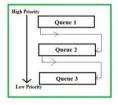
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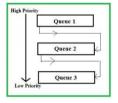
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- High priority queues have short time slices



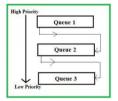
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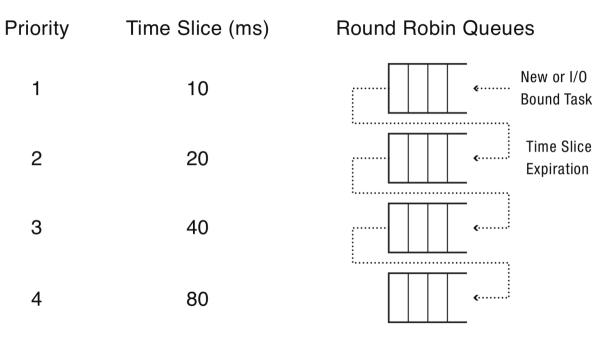
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- If time slice expires, task drops one level



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- SJF: often impossible(?) + latency variance
- RR: variable size tasks $\rightarrow \approx$ SJF.
- RR: equal size tasks \rightarrow bad
- \rightarrow CPU and I/O mixed \rightarrow SJF > RR
- MFQ balances latency, overhead and fairness

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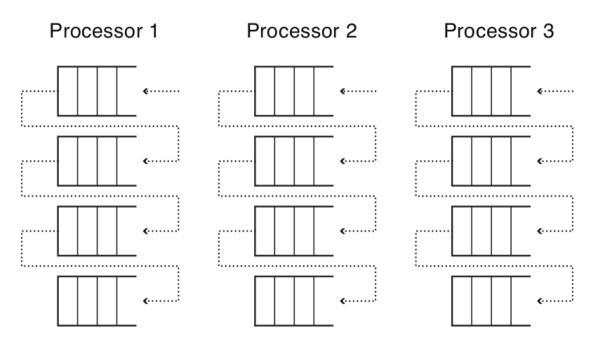
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 - ullet Lock for global MFQ lists o bad performance
 - ullet Cache slowdown (write access on one core o slower read on other core)
 - Limited cache reuse: thread's data from last time could still be in the cache (of another core!)

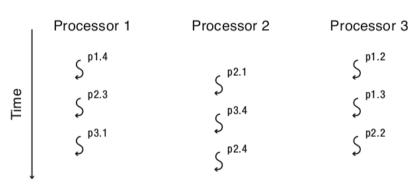
Core Affinity





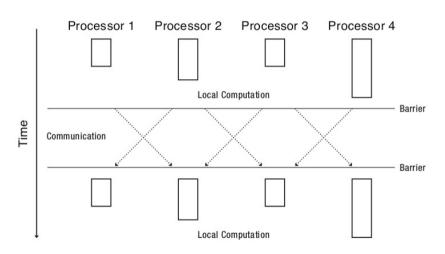
- Each core has its own thread list
- Protected by a per-core lock
- Idle cores can "steal" threads from other cores





px.y = Thread y in process x

"Just schedule threads" - yes, but ...



• Loop on each core:

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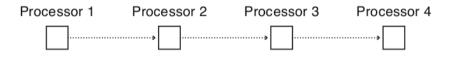
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- Examples:
 - MapReduce
 - Fluid flow over a wing
 - Most parallel algorithms can be recast in BSP
 - Sacrificing a small constant factor in performance

Producer-Consumer-Delay





• preempting one thread stalls all others

Other issues

- Critical Path Delay
 - Preempting a thread on a critical path will slow down end result



• Preemption of lock holder

Gang Scheduling

• Application splits work into threads

 $px.y = Thread \ y \ in \ process \ x$

Gang Scheduling

- Application splits work into threads
- threads always run together (if possible)

ı	Processor 1	Processor 2	Processor 3
ם	\$ p1.1 \$ p2.1 \$ p3.1	\$ p1.2 \$ p2.2 \$ p3.2	\$ p1.3 \$ p2.3 \$ p3.3

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Gang Scheduling

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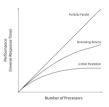
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- today: also relevant for security

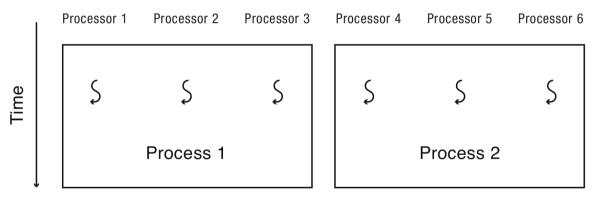
Gang Scheduling

- Some make efficient use of many cores
- some have diminishing return



Space Sharing

- ullet give two parallel programs each half of the cores o space sharing
- minimizes context switches for each core
- what we discussed before was: time sharing, time slicing (single core to multiple tasks)



Deadlocks

Classic Deadlock Example

```
wait(Resource_1);
wait(Resource_2);
use_Resource();
signal(Resource_2);
signal(Resource_1);
```

```
wait (Resource_2);
wait (Resource_1);
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signal (Resource_1);
```

Formal definition

A set of processes is deadlocked if each process in the set is waiting for an event that only another process in the set can cause.

Assumptions: processes, threads - both may be deadlocked. Number of threads, types of resources relevant.

Mutual Exclusion condition

Each resource is either currently assigned to exactly one process or is available.

Hold-and-wait condition

Processes currently holding resources that were granted earlier can request new resources

No-preemption condition

Resources previously granted cannot be forcibly taken away from a process. They must be explicitly released by the process holding them

Circular wait condition

There must be a circular list of two or more processes, each of which is waiting for a resource held by the next member of the chain

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- Detection and Recovery

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Mathematical Approach

We MUST prevent deadlocks!

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Engineering Approach

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Engineering Approach

How often does the problem occur?

Mathematical Approach

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Engineering Approach

- How often does the problem occur?
- How expensive is it to solve?

Mathematical Approach

We MUST prevent deadlocks!

Engineering Approach

- How often does the problem occur?
- How expensive is it to solve?
- Let's do a cost-benefit analysis!

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- Even detection is too expensive
- Weigh "comfort" versus "correctness"

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Example

- Resources in OS are limited
- limited number of processes or open files at any time
- assume: all active process need to do another fork or open one more file
- None are available \rightarrow deadlock!
- Now how likely is that?

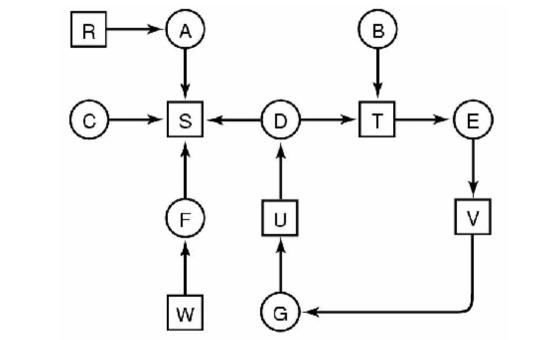
Detection and Recovery

- Don't prevent occurrence
- try to detect occurrence and deal with it when it happens
- how can we do that?
- e.g.: "draw" resource-graphs and detect circles

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• Example: is the following system deadlocked?

```
Process A holds R and wants S
Process B holds nothing but wants T
Process C holds nothing but wants S
Process D holds U but wants S and T
Process E holds T but wants V
Process F holds W but wants S
Process G holds V but wants U
```



• easy - visually

Detection

- easy visually
- but there is an algorithm too

Detection

- easy visually
- but there is an algorithm too
- many algorithms for detecting cycles in directed graphs

Simple Algorithm (useful for pthread_join)

Depth-first search in a tree

- take each node as the root of a tree
- do a depth-first search
- if we ever come back to a node we have already been to: cycle found
- when we have visited all arcs from a node: backtrack one level up
- back to start: no deadlock found
- need to try for all nodes as roots

not quite optimal

• When do we check for deadlock?

Detection

- When do we check for deadlock?
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- When do we check for deadlock?
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- And what do we do?? Preemption, roll back, kill processes?

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- manual intervention may be required

Rollback

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Rollback

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- When deadlock occurs, select process and set it back checkpoint before deadlocked resource was assigned

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- best to kill one which can easily start again (like a compiler)
- killing processes that e.g. changed databases not a great idea

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- is there an algorithm that can do this?
- Yes, if certain information is available in advance

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• Avoidance rarely practical

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- Recovery after detection difficult

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- What can we do?

- Avoidance rarely practical
- Recovery after detection difficult
- What can we do?
- Prevent by excluding one of the requirements

• no mutual exclusion - no deadlock

Wittual Exclusion

-

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- since mutual exclusion is a requirement, this is practically impossible
 - avoid using (and thus locking) a resource unless absolutely necessary
 - try to make sure that as few processes as possible may actually claim the resource

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- Alternative:
 - release all resources first whenever acquiring a new one

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Hold and Wait

Т

- prevent processes that hold resources form waiting for more resources
- e.g. require all processes to request all resources before starting execution
 - processes don't necessarily know that
 - very defensive tactics and very very bad for effective resource utilization
- Alternative:
 - release all resources first whenever acquiring a new one
 - then try to get all of them again

No preemption









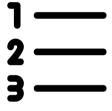




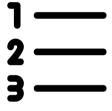
 \bullet Very difficult. Rarely possible.

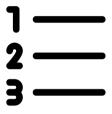






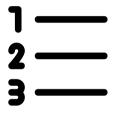






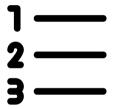
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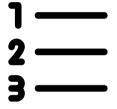
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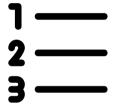
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- Better way: Provide global numbering of all resources.
- Processes can request resources, but only in numerical order.
- No cycle can exist.
- Problem: It can be difficult to find a working numbering scheme.
 What to do if resources are dynamic?

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- multiple processes: real danger of a deadlock



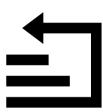




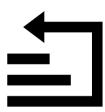




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- Phase 1: try to get locks for all records
- successful:
 - Phase 2: update records and release locks
- unsuccessful:
 - release locks and start again with Phase 1

Starvation















• Closely related to deadlocks





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- policies decide who gets which resource when
- may lead to the situation that some process never gets service even if they are not deadlocked
- can e.g. be avoided by a first-come-first-served basis