

System Level Programming

Daniel Gruss

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- Write your own implementation of malloc/free
- void *malloc(size_t size);
- void free(void *ptr);
- Write them in C++ with classes!!
- The malloc/free functions manage the Heap area and give a program the ability to request memory areas of a given size and free those areas if they are not needed anymore
- You can reuse this code in OS A2

```
int inputsize = 200;
int* buffer = malloc(inputsize*sizeof(int));
memcpy(buffer,input,inputsize)
//do something very important
free(buffer);
```

- Where in the memory is this buffer area?
- How can it be increased/decreased at runtime?



- Virtual Memory Space
- Code: Segment for the binary code
- BSS: part of Data Segment; global/static variables with known size at compiletime
- Program break shows end of Data Segment
- Program break can be increased/decerased



- Program break increased
- Heap = between end of BSS Segment and program break
- Memory addresses below program break can be used by the program



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- Heap = between end of BSS Segment and program break
- Memory addresses below program break can be used by the program
- Let's use this area for our buffer

- OS offers syscalls brk and sbrk to change the program break of the own process
- void* sbrk(intptr_t increment);
- sbrk(inc) increments the break by inc bytes
- Returns the address of the previous program break
- sbrk(0) returns current location of the break

```
void *malloc(size_t size){
  return sbrk(size)
}
```

```
void *malloc(size_t size){
  return sbrk(size)
}
Because ....
while (1)
  void * t = malloc(100);
 //do anything
  free(t);
}
```

It's not that easy, but not much harder

- Efficient usage of memory
- Reuse of freed memory areas
- Avoid fragmentation of Heap Segment

How?

- Decrease program break if possible
- Merge freed memory areas
- Split large free memory areas to the needed size

Decrease program break if possible

- If there is free memory area just below the break
- Size of this memory area



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Merge free memory areas

- Only possible to merge with next or previous area
- We have to know the size, location and state of the areas



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Reuse free areas/split large free memory areas to the needed size

- Search for a free memory area larger/equal than needed size
- Split to right size
- State of all memory areas and their location
- Size of the area to split



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- Is the memory area free?
- How large is the memory area?
- Location of the memory area?

Think about a structure which allows you to organise the Heap Segment

- Double free
- Out of memory
 - sbrk returns 0
- Buffer overflow / memory corruption
 - Special value at begin of every memory area
 - Check if first word == special value



- Consider a structure to organize the memory areas
- Decrease program break if possible
- Avoid heap fragmentation
 - Merge free neighboring memory areas
 - Split large free memory areas to the needed size
- Detect overflows, double frees and out of mem
- Your implementation has to be POSIX compliant (manpage)

- Pointer arithmetics: int* p; p+5; addr in p is increased by 5*sizeof(int)
- How many bytes does a pointer need? use typedef mempos in malloc.h
- Double-Linked-List of memory areas
- Mempos address = "valid addr"; int* i = (int*) address; *i = 100;
- Be careful to test the right malloc implementation ;)

Down the rabbit hole: Underneath x86 Linux C programs

How does a C program "work"?

- Control starts at main
- Certain functions pass control to operating system, e.g. printf has the OS write something to "standard output"
- When main returns, the program terminates gracefully
- Certain errors kill the program forcefully, e.g. with a "Segmentation fault"

How does printf "work"?

- Format string parsing, argument extraction, construct final string \rightarrow trivial
- write final string to stdout filedescriptor
- write, in turn, makes a system call (syscall) with the appropriate syscall number
- The syscall transfers control to the operating system, which executes the write on the user program's behalf

How is main called and return handled?

- Operating system does not actually run main
- Execution starts at the entry point address, where the standard library start function is located
- Initializes standard library, obtains program arguments, calls main
- After main, exit is called with the return value of main
- exit performs a syscall that terminates the program gracefully

- For C++ programs, initialization and deinitialization of global objects also has to happen before/after main, respectively
- Disassembly of a program: objdump -d
- Some interesting info (entry point address, sections, ...): readelf -a
- What symbols are visible in your program: nm
- Which shared libraries are loaded: 1dd

- Compiler produces object files for your code
- Linker takes your object files and links it with standard library objects
- gcc <code>-nostdlib</code> \rightarrow "nothing" works anymore
- Provide your own standard library!

- #include <stdio.h> still works, despite -nostdlib!
- Yes, but linking fails: undefined reference to 'printf'
- When compiling printf (...), the compiler produces something like: call printf
- The linker takes all object files, assigns ("arbitrary") addresses to all functions
- Then, all references to printf are replaced by that address

Why can the linker assign static addresses to symbols? Virtual Memory! You'll learn about that in OS ;)

Brief overview

- cdecl: "Standard" calling convention gcc uses for C programs
- syscall (not the OS/2 one): How syscalls are called
- fastcall, thiscall, pascal, ...: For other operating systems, languages, compilers, ...

We will now look at cdecl and syscall.

How do 32bit functions work?

- There is a stack somewhere in memory
- \bullet The register \mathtt{esp} points to the top of the stack
- Assembly instructions <code>push</code> and <code>pop</code> use and modify <code>esp</code>
- Another register, ebp points to the beginning of the current "stack frame"
- Each call of each function opens a new "stack frame", i.e. ${\tt ebp}$ is moved to the top of the stack
- How to restore the old ebp when the function returns? Save it on the stack!
- Local variables and parameters are always referenced relative to ebp!

Example: function

```
Consider:
int myfunc(int i)
{
    return 2*i;
}
```

This produces the following assembly:

```
pushl %ebp
movl %esp, %ebp
```

movl 8(%ebp), %eax
addl %eax, %eax

popl %ebp ret

How does the call work?

- Function refers to parameters on the stack
- So we will have to push them on the stack (right to left)
- \bullet call function
- \bullet Return value is then in eax
- Remove parameters from stack again ("caller cleanup")
- Except for floating point values, but we won't cover that here

myfunc(1);

This produces the following assembly:

subl \$4, %esp
movl \$1, (%esp)
call myfunc
addl \$0, %esp

How does a system call work?

- Put all parameters into registers
- Request an interrupt
- The interrupt handler will run in kernel mode and use values from registers
- \bullet Return value is then again in eax
- What happens in kernel mode? You will find out in Operating Systems!
A6 - Inline Assembly and Calling Conventions

Have you ever wondered what happens in your CPU when you call a function?



```
Callee
void foo()
{
// do stuff...
}
```

Let's take a look at the compiler output

objdump -d <executable>

Caller (ASM)

```
main:
    # ...
    call foo
    # ...
```

Callee (ASM) foo: # do stuff... ret

Caller (ASM) main: # ... call foo # ...

Callee (ASM)

foo:

do stuff...

 \mathbf{ret}

Stack



Function Calls

Caller (ASM) main: # ... call foo \longrightarrow address onto stack and jumps to # ... target

Callee (ASM)

foo:

```
# do stuff...
```

 \mathbf{ret}



















```
Caller
int main()
{
    char arg1 = 5;
    char arg2 = 7;
    int retval = foo(arg1, arg2);
}
How does this...
```

Callee						
int foo(char	a,	char	b)			
{						
<pre>return a ></pre>	b;					
}						



```
Caller
int main()
{
    char arg1 = 5;
    char arg2 = 7;
    int retval = foo(arg1, arg2);
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```





...back here?

• Registers

- Registers
 - Which ones?

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 - Which ones?
 - What if we don't have enough registers?
- Memory (i.e. on the stack)
 - In which order?

A calling convention defines the interaction between functions on the level of CPU-instructions

- Function parameters
- Return values
- Registers that need to be saved/restored across function calls

Calling conventions are not only relevant within a single binary. All interfaces between binary modules need to conform to a common interface to be compatible.

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- Object files that are linked together at compile time
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- \Rightarrow Defined as part of an ABI (Application Binary Interface)
 - A complete ABI also defines the executable format (e.g. ELF), instruction set, ...

The used ABI/calling convention depends on

- CPU architecture
- Operating system
- Compiler

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Mostly standardized

Commonly used calling conventions

	Linux	Windows
i386	cdecl	cdecl, stdcall, fastcall,
×86_64	System V amd64 ABI	Microsoft ×64

System calls usually use a different calling convention than the rest of the userspace

	Linux	Windows
i386	cdecl	cdecl, stdcall, fastcall,
×86_64	System V amd64 ABI	Microsoft ×64

Main difference: Function arguments on stack vs. in registers

In this assignment you will need to write (inline) assembly.

No C code allowed!

GCC allows you to write assembly code inside C functions

```
GCC Inline Assembly
 int foobar(uint64 t* result) {
   uint64 t a = 3;
   uint64 t b = 4:
   asm("movq %[op1], %%rax\n"
       "addg %[op2], %%rax\n"
       "movg %%rax, %[res]\n"
   :[res] "=m" (*result) // output (memory location, not value)
   :[op1]"m"(a), // input (op1 in memory)
   [op2]"r"(b) // (op2 in register)
   :"rax", "cc"); // clobbers the rax register and status flags ("m" output
      constraint -> no need to explicity list "memory")
```

Your Tasks

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- Tasks 2b Implement a function in assembly (x86 64-bit)